

## **Power Optimization in Counters Using Gray Coding**

**Lowrence Khanna, Ms. Rimmy Chhabra, Ayushman Choudhary, Kanika**

*QUANTUM UNIVERSITY ROORKEE*

*lowrencekhanna69@gmail.com, rimmy.cse@quantumeducation.in, choudharyayushmaan575@gmail.com, kanikapundir18@gmail.com*

\*\*\*

**Abstract** - Digital counters are the basic building blocks in electronic systems. They are used in processors, communication circuits, timers, and embedded devices. But the normal binary counters consist of a problem-in the counting process, multiple bits suffer from high switching activity and their bits change simultaneously. And that's why the power consumption increases. Due to this there is a sudden increase in the switching activity. And because of this power consumption also increases. In today's world there is a need of using low power consumption designs specially for battery operated devices.

In this research paper we will perform the comparison between binary counter and gray counter. Let's see which counter performs how much switching, and how the gray coding improves the power efficiency.

**Keywords:** Digital Counters; Power Optimization; Energy-Efficient Circuit; Sequential Logic; Bit Transition Reduction

### **Introduction**

In digital electronics nowadays, power consumption has become the most important factor for today's generation. Especially for the battery-operated devices like smartphones, smart watches, IoT gadgets, and medical devices. This device contains the small digital components inside them that affect the total power consumption of that particular device. And counters play a vital role in these components. Mostly counters are the part of every digital system-processors, timers, communication modules, control circuits used in all fields. Because counters operate the system continuously their switching activity increases the overall dynamic power consumption of any system.

Traditional binary counters consist of a problem when a counter goes from one state to another so most of the time the bit toggles itself. Example: 0111 se 1000, here every bit was changed. This multi-bit switching increases the dynamic power. As well as generating electromagnetic interference.

And this problem is solved by the gray code counters. The plus of the gray code counters is that only single bit changes in consecutive numbers. This is called a single bit transition. Because a single bit toggles on each step. And it reduces the

switching activity. And when the switching reduces the power consumption and noise also reduces. Gray counters give simple, power efficient and stable outputs without adding any extra hardware complexity. That's why in today's world low power electronics are the most effective and popular alternatives.

### **Objective**

**To study** the switching behavior of gray code counters and binary code counters deeply. The first goal of this research is to study how the both counters change their states. Number of flips of bits in each counter. And to study in detail where the unnecessary switching occurs.

**Analyzing** the effect of bit transitions in dynamic power. The more bits that flip during a transition, the more power the circuit consumes. Multi bit switching occurs in binary counters and the single bit switching in gray counters. How much the effect of this difference in the power consumption is the objective of this research.

**Simulate** the binary and gray code counters after designing, and then compare their performances. Verilog/VHDL like tools are used to design both of these counters.

By simulation we will get to know the differences in performance, power consumption complexity, and efficiency in between these counters.

**To prove** the power optimization practically by using gray coding. To show how much the gray counters save the power on compared to binary counters by using the Switching activity files (SAIF) and power analyzer tools.

**To identify** the real-world applications where the gray code counters are used.

### **Problem statement**

Binary counters experience higher switching activity because the bits change simultaneously while changing from one state to another. And this causes many challenges for today's world digital systems. Firstly, it increases the dynamic power consumption and every bit that changes or changes requires energy. And if we use higher power, it increases the heat generation in the circuit which affects the lifespan of the electronic components. In battery powered and portable devices the power consumption is inefficient and

causes high excessive switching activity and it leads to reducing the battery life.

And therefore, we need a proper counter architecture which reduces the switching activity and it reduces the power consumption without adding the extra hardware complexity and affecting performances.

### Literature Overview

Low power circuits are one of the most important topics in today's generation. Because every device like mobile, sensor, embedded system wants to offer more work in low power consumption.

Research proposes many techniques like clock gating, voltage scaling, and optimized state encoding but gray coding is said to be the most efficient coding. Especially in the case of counters.

Studies say that most of the bits flips together at the time of changing the state from one to another in binary counters. And because of this extra switching occurs that leads to higher wastages of power.

On the other hand, single bit was flipped in gray code counters and due to this;

- Switching activity reduces
- Less glitches
- Single is stabled
- Reduces electromagnetic interference.

Research also shows that gray code counters are useful in **encoders, sensors, ADCs, memory addressing, communication systems**, and low-power devices.

All these findings prove that gray code counters are a more power efficient method in this digital world.

### Methodology

#### Literature review

Firstly-we have seen all existing research – how the binary counters-works, what is gray code, and what are the techniques used in low power circuits. Through all this we understood the background.

#### Analysis of switching activity

Then we observe the bit changes in our binary counter-means after every clock how many bits are toggled. It is the activity that increases the dynamic power. We have known the power formula  $p$  is directly proportional to  $CV^2f$ . By this we get to know how much power will be consumed by the switching activity.

### Gray code counter design

After that we designed the gray code counter, in this a single bit changes in each next state, we implemented this by the combinational logic and flip flops. So that we don't have the need of any extra hardware.

### Simulation and comparison

We have tuned both the binary and gray counters in simulation tools (Verilog/VHDL). We have observed the waveforms and counted the bits changed in each clock. And from here we get to know the real difference between the both counters.

#### • Power estimation

Lower switching activity in gray counters meant reduced dynamic power. That's why we compared the total bits toggled in both counters and estimated the power differences.

#### • result interpretation

At last-we analyzed all the results-and got to know that switching activity is low in gray code counters. And power is also reduced significantly.

### Switching Analysis

When a counter moves from one binary pattern to another some of the bits change 0 to 1 or 1 to 0. And due to these flips the capacitance of the circuits goes to charges or discharges. And energy is reduced. That is why the number of **bit-toggles per transition** is directly proportional to switching activity.

#### Example:

#### Binary Counter Switching

- In binary counting, multiple bits can change at the same time.
- Example 3-bit binary:  
000 → 001(1 bit changes)  
001 → 010(2 bits change)  
011 → 100(3 bits change)
- Because 2–3 bits flip together, switching activity is high → more dynamic power.

#### Gray Counter Switching

- In Gray code, only one-bit changes at every step.
- Example 3-bit Gray:

000 → 001(1 bit)

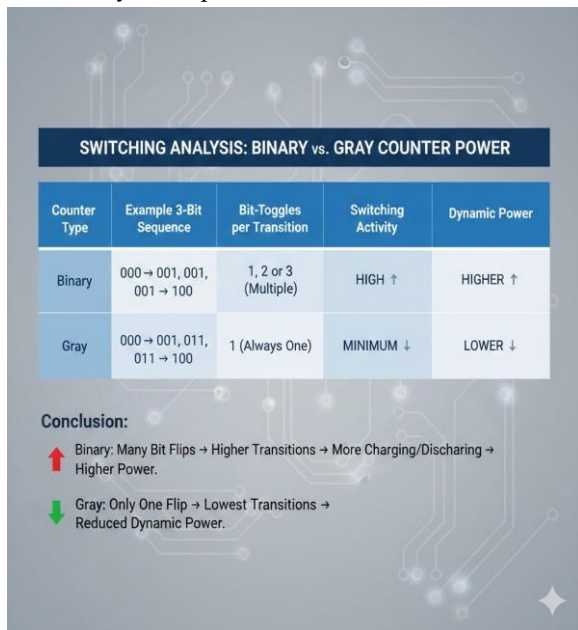
001 → 011(1 bit)

011 → 010(1 bit)

- Always 1 bit flip per step → minimum switching → lower dynamic power.

## Result

- Binary: many bit flips → higher transitions → more charging/discharging → higher power.
- Gray: only one flip → lowest transitions → reduced dynamic power.



## Experimental Results

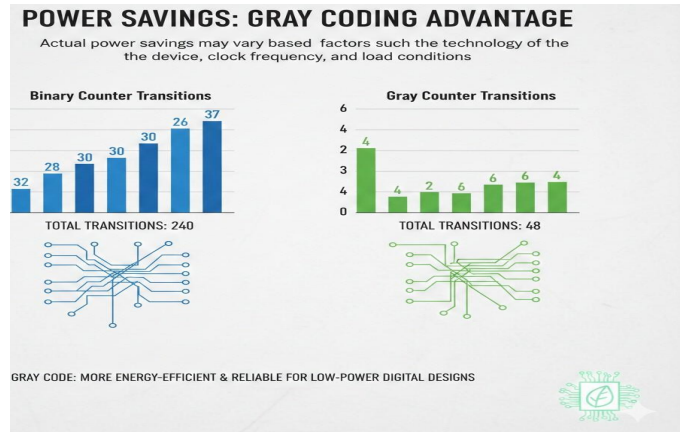
Simulation shows us how much the differences are there in both the counters.

While moving from one state to another in binary counters the 2-3 bits flips together. And because of this, switching activity increases. Most of the time it creates many glitches that creates noises and wastes our power consumption.

While on the other hand in **gray code counters** single bit changes on each step and due to these transitions are smoother and more stabled in them. And that's why switching activity reduces. Results show us in gray counter **40%–60% switching activities are reduced.**

How much power is saved totally depends upon the technologies, clock frequency, and load's frequency.

If we show the graphical representation like tables and charts so they clearly show us the



differences between the transitions in gray and binary code counters.

And that's why gray coding is more effective and reliable in low-power digital Circuits.

## Applications

As we know that gray code counters produce single bit change in each step and because of this the code is stable and noise free. Gray code counters mostly used in the systems that offer less glitches and power savings.

They are widely used in:

- **Low-power processors** – to reduce dynamic power in internal counting operations.
- **Rotary encoders and motion sensors** – to avoid errors when detecting position or movement.
  - **Analog-to-digital converters (ADCs)** – to ensure stable, glitch-free output during conversion.
  - **Communication systems** – for error-free data transmission and addressing.
  - **Robotics and automation** – where precise movement tracking is required.
- **Position-tracking devices** – to measure angles, rotations, and direction changes without noise.

### Conclusion

At last, the overall conclusion is that gray code counters offer us an easy and effective way to reduce power in digital circuits. Because a single bit changes at a time, and because of this switching is reduced.

Moreover, switching transitions are very low in it and because of this it is very reliable for modern world systems, where power speed and reliability are one of the most important factors.

Gray code counters reduce the unnecessary bit toggling; this reduces the dynamic power, EMI, and glitches.

All this results a circuit works efficiently where in high frequency or even in noise-sensitive conditions.

And at the last but not the least gray coding gives an engineer a compact, energy efficient, and creates reliable digital designs easily

This study shows that Gray Coding is a practical method to design power-efficient counters without adding extra complexity to the circuit.

### References

[1] Digital Design by M. Morris Mano.

[2] Low-Power Digital CMOS Design – Kaushik Roy

[3] Research papers on Gray coding and power optimization

[4] Standard digital electronics journals and IEEE resources

[5] Rabaey, J. M., Chandrakasan, A., & Nikolic, B. (2003). "Digital Integrated Circuits: A Design Perspective," Prentice Hall.

[6] A foundational VLSI design textbook covering switching power, CMOS behavior, and optimization techniques.

[7] Chandrakasan, A., Sheng, S., & Brodersen, R. W. (1992). "Low-Power CMOS Digital Design," IEEE Journal of Solid-State Circuits.

[8] Wakerley, J. F. (2005). "Digital Design: Principles and Practices," Prentice Hall.

[9] Patterson, D., & Hennessy, J. (2017). "Computer Organization and Design," Morgan Kaufmann.

[10] Tsividis, Y. (1999). "Mixed Analog-Digital VLSI Devices and Technology," McGraw-Hill.

[11] Shrivastava, A., & Sarma, D. (2016). "Design and Analysis of Low-Power Gray Code Counter," International Journal of Electronics & Communication Engineering.

[12] Agrawal, A., & Rao, V. (2018). "Switching Activity Reduction in Counters Using Gray Coding," IEEE Conference on VLSI Design.

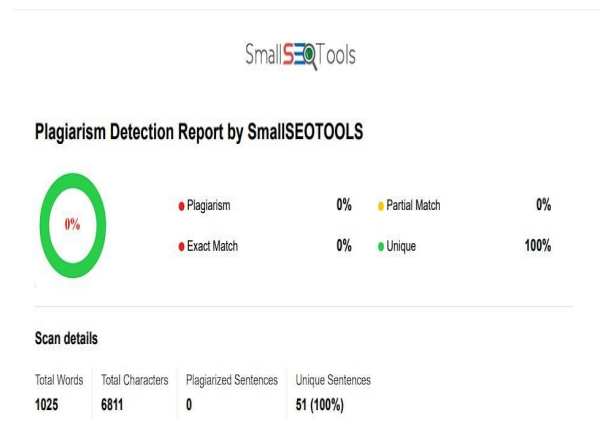
[13] IEEE Transactions on Low Power Electronics and VLSI Systems

[14] Hamming, R. W. (1950). "Error Detecting and Error Correcting Codes," Bell System 14.

Roth, C. H. Jr., "Fundamentals of Logic Design," Cengage Learning.

[15] Weste, N. H. E., & Harris, D. (2010). *CMOS VLSI Design: A Circuits and Systems Perspective*. Addison-Wesley.

### Plagiarism in the research paper



### AI Detention

